

1 Mass Conservation

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Let

$$\begin{aligned}\Phi_t &: \Omega_0 \rightarrow \Omega_t, & \mathbf{x}_0 &\mapsto \mathbf{x} = \mathbf{p}(t, t_0, \mathbf{x}_0), \\ \Phi_{-t} &: \Omega_t \rightarrow \Omega_0, & \mathbf{x} &\mapsto \mathbf{x}_0 = \mathbf{q}(t, t_0, \mathbf{x}) = \mathbf{p}(t_0, t, \mathbf{x}),\end{aligned}$$

be the flow of the vector field \mathbf{V} with single field lines characterized by $\mathbf{p}(t, t_0, \mathbf{x}_0)$

$$\frac{\partial \mathbf{p}}{\partial t} = \mathbf{V}(t, \mathbf{p}(t)) = \mathbf{V} \circ \mathbf{p}, \quad \mathbf{p}(t_0, t_0, \mathbf{x}_0) = \mathbf{x}_0, \quad (1)$$

i.e., for each starting point \mathbf{x}_0 is \mathbf{p} the solution of

$$\frac{d\mathbf{x}}{dt} = \mathbf{V}(t, \mathbf{x}). \quad (2)$$

Ω_t a volume comoving with the flow and J the Jacobian of the transformation,

$$\Omega_t = \Phi_t(\Omega_0), \quad J(t, t_0, \mathbf{x}_0) = \frac{\partial(p^1, p^2, \dots, p^n)}{\partial(x_0^1, x_0^2, \dots, x_0^n)} = \det\left(\frac{\partial p^i}{\partial x_0^k}\right). \quad (3)$$

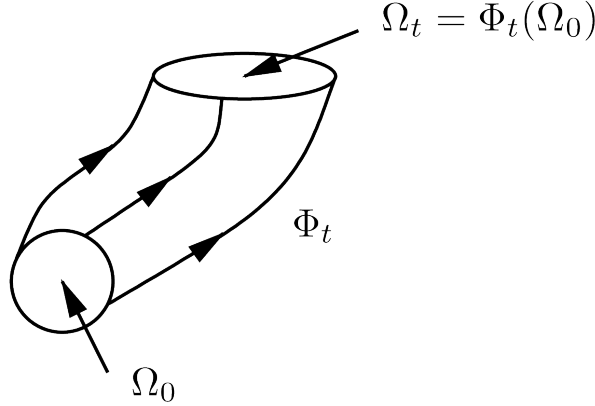


Figure 1: Integral lines of a vector field.

The flow $x^i = p^i(t, t_0, \mathbf{x}_0)$ induces a variable transformation in the differential volume element (hodge dual of 1),

$$\begin{aligned} *1 &= \frac{1}{n!} dx^{i_1} \wedge dx^{i_2} \wedge \dots \wedge dx^{i_n} \varepsilon_{i_1 i_2 \dots i_n} \sqrt{g(\mathbf{x})} \\ &= \frac{1}{n!} \left(\frac{\partial p^{i_1}}{\partial x_0^{j_1}} dx_0^{j_1} \right) \wedge \left(\frac{\partial p^{i_2}}{\partial x_0^{j_2}} dx_0^{j_2} \right) \wedge \dots \wedge \left(\frac{\partial p^{i_n}}{\partial x_0^{j_n}} dx_0^{j_n} \right) \varepsilon_{i_1 i_2 \dots i_n} \sqrt{g \circ \mathbf{p}} \\ &= \frac{1}{n!} \frac{\partial p^{i_1}}{\partial x_0^{j_1}} \frac{\partial p^{i_2}}{\partial x_0^{j_2}} \dots \frac{\partial p^{i_n}}{\partial x_0^{j_n}} \varepsilon_{i_1 i_2 \dots i_n} dx_0^{j_1} \wedge dx_0^{j_2} \wedge \dots \wedge dx_0^{j_n} \sqrt{g \circ \mathbf{p}} \\ &= \frac{1}{n!} J(t, t_0, \mathbf{x}_0) \varepsilon_{j_1 j_2 \dots j_n} \sqrt{g \circ \mathbf{p}(t, t_0, \mathbf{x}_0)} dx_0^{j_1} \wedge dx_0^{j_2} \wedge \dots \wedge dx_0^{j_n}, \quad (4)\end{aligned}$$

where

$$\det(A) = \varepsilon_{i_1 i_2 \dots i_n} a_{1 i_1} a_{2 i_2} \dots a_{n i_n}$$

has been used.

$$\begin{aligned}
& \frac{d}{dt} \int_{\Omega_t} dx^1 \wedge dx^2 \wedge \dots \wedge dx^n \sqrt{g(\mathbf{x})} \rho(t, \mathbf{x}) \\
&= \frac{d}{dt} \int_{\Omega_0} dx_0^1 \wedge dx_0^2 \wedge \dots \wedge dx_0^n J(\sqrt{g}\rho) \circ \mathbf{p} \\
&= \int_{\Omega_0} dx_0^1 \wedge dx_0^2 \wedge \dots \wedge dx_0^n \frac{\partial}{\partial t} [J(\rho\sqrt{g}) \circ \mathbf{p}] \\
&= \int_{\Omega_0} dx_0^1 \wedge dx_0^2 \wedge \dots \wedge dx_0^n \left[\frac{\partial}{\partial t} (\sqrt{g} \circ \mathbf{p}) J \rho \circ \mathbf{p} + J \sqrt{g} \circ \mathbf{p} \left(\frac{\partial \rho}{\partial t} + V^k \frac{\partial \rho}{\partial x^k} \right) \circ \mathbf{p} \right] \\
&= \int_{\Omega_0} dx_0^1 \wedge dx_0^2 \wedge \dots \wedge dx_0^n J \sqrt{g} \circ \mathbf{p} \left(\rho \frac{1}{\sqrt{g}} \frac{\partial}{\partial x^k} (\sqrt{g} V^k) + \frac{\partial \rho}{\partial t} + V^k \frac{\partial \rho}{\partial x^k} \right) \circ \mathbf{p} \\
&= \int_{\Omega_t} dx^1 \wedge dx^2 \wedge \dots \wedge dx^n \sqrt{g} \left[\rho \operatorname{div} \mathbf{V} + \frac{\partial \rho}{\partial t} + \mathbf{V} \cdot \nabla \rho \right] \\
&= \int_{\Omega_t} dx^1 \wedge dx^2 \wedge \dots \wedge dx^n \sqrt{g} \left[\frac{\partial \rho}{\partial t} + \operatorname{div} (\rho \mathbf{V}) \right]. \tag{5}
\end{aligned}$$

Time derivative of Jacobian,

$$\begin{aligned}
\mathbf{A}^{-1} \mathbf{A} &= \mathbf{I}, \quad \mathbf{C}^T \mathbf{A} = \det(\mathbf{A}) \mathbf{I}, \quad J \delta^i_k = c_j^i a^j_k, \\
\frac{\partial}{\partial t} J &= \frac{\partial}{\partial t} (c_j^{(i)} a^j_{(i)}) = c_j^i \frac{\partial}{\partial t} (a^j_i) = c_j^i \frac{\partial}{\partial t} \left(\frac{\partial p^j}{\partial x_0^i} \right) \\
&= c_j^i \frac{\partial}{\partial x_0^i} \frac{\partial p^j}{\partial t} = c_j^i \frac{\partial}{\partial x_0^i} (V^j \circ \mathbf{p}) = c_j^i \left(\frac{\partial V^j}{\partial x^k} \circ \mathbf{p} \right) \frac{\partial p^k}{\partial x_0^i} \\
&= c_j^i a^k_i \frac{\partial V^j}{\partial x^k} \circ \mathbf{p} = J \delta_j^k \frac{\partial V^j}{\partial x^k} \circ \mathbf{p} = J \frac{\partial V^i}{\partial x^i} \circ \mathbf{p}. \tag{6}
\end{aligned}$$

$$\frac{\partial}{\partial t} (\sqrt{g} \circ \mathbf{p}) = \left(V^k \frac{\partial}{\partial x^k} \sqrt{g} \right) \circ \mathbf{p} \tag{7}$$

$$\frac{\partial}{\partial t} (\sqrt{g} \circ \mathbf{p}) J = \sqrt{g} \circ \mathbf{p} J \left[\frac{1}{\sqrt{g}} \frac{\partial}{\partial x^k} (\sqrt{g} V^k) \right] = J (\sqrt{g} \operatorname{div} \mathbf{V}) \circ \mathbf{p}. \tag{8}$$

Change of differential volume valid for the flow of any time dependent vector field

$$\frac{\partial}{\partial t} (\sqrt{g} \circ \mathbf{p} J) = J (\sqrt{g} \operatorname{div} \mathbf{V}) \circ \mathbf{p}. \quad (9)$$

Conservation of total mass implies

$$\frac{\partial \rho}{\partial t} + \operatorname{div} (\rho \mathbf{V}) = 0. \quad (10)$$

Liouville's theorem says that in case of zero divergence of the vector field \mathbf{V} , the mass density along field lines is constant,

$$\frac{d}{dt} (\rho \circ \mathbf{p}) = \frac{\partial \rho}{\partial t} + \mathbf{V} \cdot \nabla \rho = 0. \quad (11)$$

The theorem also says that phase space volume is conserved even in the case of a time dependent vector field.

In kinetic plasma theory, particle conservation governed by the single particle distribution function

$$\int dx^3 dv^3 f(t, \mathbf{x}, \mathbf{v}) = N, \quad (12)$$

and the divergence free Hamiltonian vector field Vlasov's equation is obtained

$$\frac{\partial f}{\partial t} + \mathbf{v} \cdot \frac{\partial f}{\partial \mathbf{x}} + \frac{e}{m} \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right) \cdot \frac{\partial f}{\partial \mathbf{v}} = 0. \quad (13)$$

Expressed by Liouville's theorem, the distribution function is constant along the integral lines of Hamiltonian vector fields.

The characteristic equations are

$$\begin{aligned} \dot{\mathbf{x}} &= \mathbf{v}, \\ \dot{\mathbf{v}} &= \frac{e}{m} \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right), \end{aligned}$$

and, therefore,

$$\operatorname{div} \mathbf{V} = \frac{\partial}{\partial \mathbf{x}} \cdot \mathbf{v} + \frac{\partial}{\partial \mathbf{v}} \cdot \frac{e}{m} \left(\mathbf{E} + \frac{1}{c} \mathbf{v} \times \mathbf{B} \right) = 0,$$

because

$$\frac{\partial}{\partial \mathbf{v}} \cdot (\mathbf{v} \times \mathbf{B}) = 0.$$